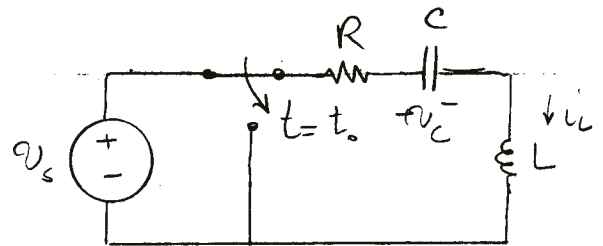


SECOND ORDER CIRCUITS

Second order circuits contain two storage elements (2 Capacitor or 2 inductor or one of each)

- The solution to this circuits always results in 2nd order differential equation & requires two initial conditions
- Solution Method is similar to 1st order circuits

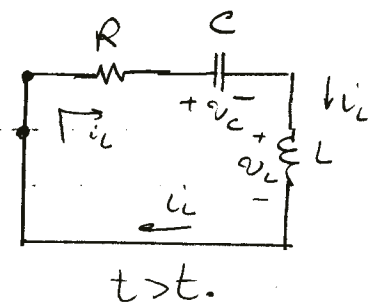
SERIES RLC circuits, Natural Response



DC steady-state analysis will determine the initial conditions:

$$v_c(t = t_0^+) \text{ \& \; } i_L(t = t_0^+)$$

$$\text{KVL: } \begin{cases} R i_L + v_c + v_L = 0 \\ v_L = L \frac{di_L}{dt} \\ i_c = i_L = C \frac{dv_c}{dt} \end{cases}$$



$$\begin{cases} L \frac{di_L}{dt} + R i_L + v_c = 0 \\ i_L = C \frac{dv_c}{dt} \end{cases}$$

Substitute for i_L in the first equation noting $\frac{di_L}{dt} = C \frac{d^2 v_c}{dt^2}$

$$LC \frac{d^2 v_c}{dt^2} + RC \frac{dv_c}{dt} + v_c = 0$$

above is a 2nd order differential equation for v_c . We need two initial conditions for v_c , typically

$$v_c(t=t_0^+) \quad \& \quad \left. \frac{dv_c}{dt} \right|_{t=t_0^+}$$

$v_c(t=t_0^+)$ is usually found from DC steady state analysis. In order to find $\left. \frac{dv_c}{dt} \right|_{t=t_0^+}$, look at equations governing the circuit & choose one which include both i_L & $\frac{dv_c}{dt}$

$$i_L = C \frac{dv_c}{dt}$$

Since the above equation is correct at all times $t > t_0$, thus

$$i_L(t=t_0^+) = C \left. \frac{dv_c}{dt} \right|_{t=t_0^+} \Rightarrow \left. \frac{dv_c}{dt} \right|_{t=t_0^+} = \frac{i_L(t=t_0^+)}{C}$$

2nd initial condition.

Note that we could have, alternatively, found a 2nd order differential equation in i_L by differentiating the first equation & substituting for $\frac{dv_c}{dt}$

$$L \frac{di_L}{dt} + Ri_L + v_c = 0$$

$$L \frac{d^2 i_L}{dt^2} + R \frac{di_L}{dt} + \frac{dv_c}{dt} = 0 \quad \leftarrow \quad \frac{dv_c}{dt} = \frac{i_L}{C}$$

$$\underline{LC \frac{d^2 i_L}{dt^2} + RC \frac{di_L}{dt} + i_L = 0}$$

The initial conditions for this equation is also found as before
 $i_L(t=t_0^+)$ from DC steady state

$$L \frac{di_L}{dt} + Ri_L + v_c = 0 \Rightarrow \left. \frac{di_L}{dt} \right|_{t=t_0^+} = -\frac{R}{L} i_L(t=t_0^+) - \frac{1}{L} v_c(t=t_0^+)$$

Solution: try $v_c = K e^{st} \rightarrow \frac{dv_c}{dt} = K s e^{st}, \frac{d^2 v_c}{dt^2} = K s^2 e^{st}$

Thus: $LC (K s^2 e^{st}) + RC (K s e^{st}) + K e^{st} = 0$

or $LC s^2 + RC s + 1 = 0$ ↔ Characteristic Equation

All 2nd order differential equation result in a 2nd order characteristic equation $\Rightarrow$ two roots s_1 & s_2

$$v_c = K_1 e^{s_1 t} + K_2 e^{s_2 t}$$

For special case of $s_1 = s_2 \Rightarrow v_c = K_1 t e^{s_1 t} + K_2 e^{s_1 t}$

In order to review the general behavior of 2nd order circuits, rewrite the characteristic equation as

$$s^2 + \frac{R}{L} s + \frac{1}{LC} = 0$$

or in general

$$s^2 + 2\alpha s + \omega_0^2 = 0 \Rightarrow s = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

(for above circuit, $\alpha = \frac{R}{2L}, \omega_0^2 = \frac{1}{LC}$) α : Neper frequency
 ω_0 : Resonant radian freq.

Depending on values of α & ω_0^2 , we can have 1) two real roots, 2) two complex roots, 3) two purely imaginary roots, 4) a 2nd order root ($s_1 = s_2$)

Case I $\alpha = 0, \omega_0^2 > 0$ ($R = 0$ in series RLC)

$$s^2 + \omega_0^2 = 0 \Rightarrow s_1 = +j\omega_0, s_2 = -j\omega_0 \quad (j^2 = -1)$$

Then $v_c = K_1 e^{j\omega_0 t} + K_2 e^{-j\omega_0 t} = K \cos(\omega_0 t + \phi_0)$
↙ by Euler's formula

K & Φ_0 are constants of integration & can be found from the initial conditions.

For our example

$$\begin{cases} v_c(t=t_0^+) = v_s = K \cos(\omega_0 t_0 + \Phi_0) \\ \left. \frac{dv_c}{dt} \right|_{t=t_0^+} = 0 = -K\omega_0 \sin(\omega_0 t_0 + \Phi_0) \Rightarrow \omega_0 t_0 + \Phi_0 = 0 \\ \Phi_0 = -\omega_0 t_0 \end{cases}$$

$$v_s = K \cos(\omega_0 t_0 - \omega_0 t_0) = K \Rightarrow K = v_s$$

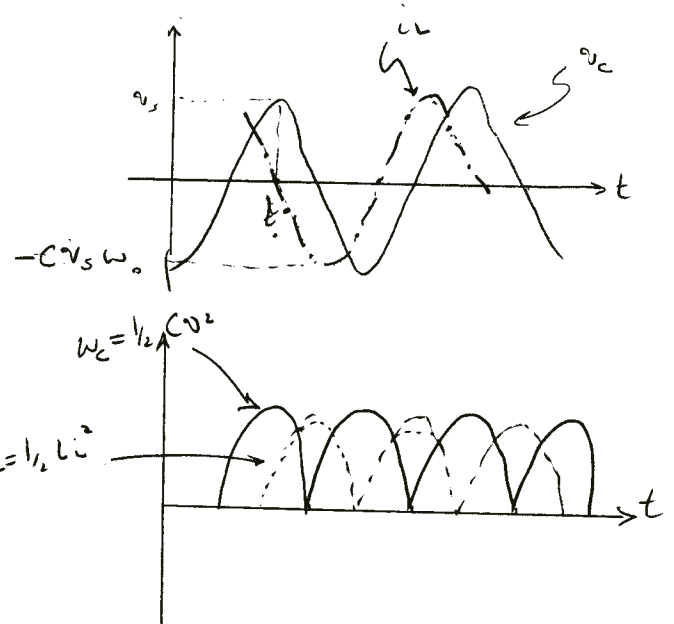
Solution

$$\begin{cases} v_c = v_s \cos[\omega_0(t-t_0)] \\ i_L = C \frac{dv_c}{dt} = -Cv_s \omega_0 \sin[\omega_0(t-t_0)] \end{cases}$$

$$\omega_0 = \sqrt{\frac{1}{LC}}$$

This is harmonic Oscillator

Note at the $t=t_0$, Capacitor is fully charged ($v_c = v_s$) & inductor is fully discharged ($i_L = 0$). As the switch is moved to position B, capacitor discharges (v_c decrease) & inductor charges



up (i_L increases). Once capacitor is fully discharged ($v_c = 0$), the inductor is fully charged & then it starts to discharge, charging up the capacitor. This is very similar to the motion of a pendulum.

$$w_C = \frac{1}{2} C v_c^2 = \frac{C}{2} v_s^2 \cos^2[\omega_0(t-t_0)]$$

$$\begin{aligned} w_L &= \frac{1}{2} L i_L^2 = \frac{1}{2} L C^2 v_s^2 \omega_0^2 \sin^2[\omega_0(t-t_0)] \\ &= \frac{1}{2} C v_s^2 \sin^2[\omega_0(t-t_0)] \end{aligned}$$

$$w_{\text{total}} = w_C + w_L = \frac{C}{2} v_s^2 = w_C(t=t_0^+)$$

Case II: $\alpha \neq 0$ but α small ($\alpha^2 < \omega_0^2$)

89

Underdamped

$$\left(\frac{R}{L}\right)^2 < \frac{1}{LC} \Rightarrow R^2 < \frac{L}{2C}$$

When a resistor is present, the total stored energy is not constant anymore.

During each oscillation, a part of stored energy is dissipated by the resistor. Therefore, the solution should be like of a harmonic oscillator but with amplitude of oscillation being reduced in time (similar to a real pendulum, in which friction would stop the pendulum eventually).

$$s^2 + 2\alpha s + \omega_0^2 = 0 \Rightarrow s = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

Define $\omega_d^2 = \omega_0^2 - \alpha^2 > 0 \Rightarrow s = -\alpha \pm j\omega_d$

Solution
$$v_c(t) = K_1 e^{(-\alpha + j\omega_d)t} + K_2 e^{(-\alpha - j\omega_d)t}$$

$$= e^{-\alpha t} [K_1 e^{j\omega_d t} + K_2 e^{-j\omega_d t}]$$

$$v_c = K e^{-\alpha t} \cos(\omega_d t + \phi_0)$$

using Euler's formula as before

Again K & ϕ_0 are found from our initial condition

$$\textcircled{1} \left. \frac{dv_c}{dt} \right|_{t=t_0^+} = K \left\{ -\alpha \cos(\omega_d t_0 + \phi_0) e^{-\alpha t_0} - \omega_d \sin(\omega_d t_0 + \phi_0) e^{-\alpha t_0} \right\} = 0$$

$$\tan(\omega_d t_0 + \phi_0) = -\frac{\alpha}{\omega_d} \Rightarrow \phi_0 + t_0 \omega_d = \tan^{-1}\left(-\frac{\alpha}{\omega_d}\right)$$

$$\textcircled{2} v_0 = v_c(t_0^+) = K e^{-\alpha t_0} \cos(\omega_d t_0 + \phi_0) \Rightarrow K$$

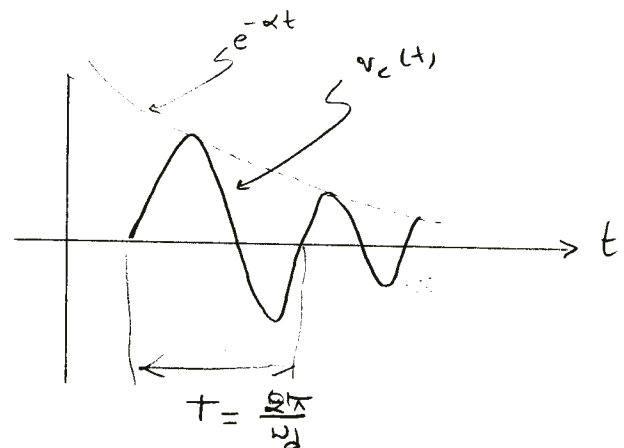
Note, because $\omega_d = \sqrt{\omega_0^2 - \alpha^2} < \omega_0$

The frequency of oscillations

become slower!

ω_d : damped frequency

α : damping coefficient



Case III, $\alpha \neq 0$ & $\alpha^2 = \omega_0^2$

Critically damped

90

$$S^2 + 2\alpha S + \omega_0^2 = 0 \Rightarrow S^2 + 2\alpha S + \alpha^2 = 0 \Rightarrow S_1 = S_2 = -\alpha$$

Solution

$$v_c = K_1 e^{-\alpha t} + K_2 t e^{-\alpha t}$$

I.C. $v_c(t=t_0^+) = v_s \Rightarrow K_1 e^{-\alpha t_0} + K_2 t_0 e^{-\alpha t_0} = v_s \Rightarrow K_1 + K_2 t_0 = v_s e^{\alpha t_0}$

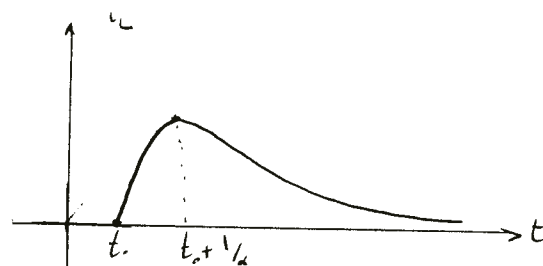
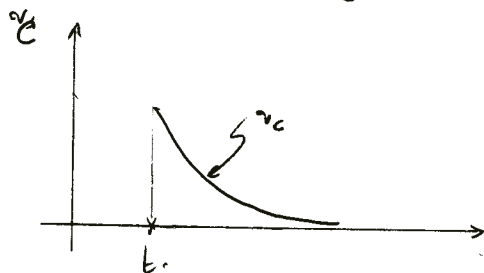
$$\left. \frac{dv_c}{dt} \right|_{t=t_0^+} = 0 = \left[-\alpha K_1 e^{-\alpha t} + K_2 e^{-\alpha t} - \alpha K_2 t e^{-\alpha t} \right] \Big|_{t=t_0^+}$$

$$-\alpha K_1 e^{-\alpha t_0} + K_2 e^{-\alpha t_0} - \alpha K_2 t_0 e^{-\alpha t_0} = 0 \Rightarrow \alpha K_1 + K_2 + \alpha K_2 t_0 = 0$$

$$\therefore K_2 = +\alpha (K_1 + K_2 t_0) = +\alpha v_s e^{\alpha t_0}$$

$$K_1 = v_s e^{\alpha t_0} - \alpha t_0 v_s e^{\alpha t_0} = (1 - \alpha t_0) v_s e^{\alpha t_0}$$

$$v_c = (1 - \alpha t_0) v_s e^{-\alpha(t-t_0)} + \alpha v_s t e^{-\alpha(t-t_0)}$$



Case IV

$$\alpha^2 > \omega_0^2$$

Over damped

(α can be zero)

$$S^2 + 2\alpha S + \omega_0^2 = 0$$

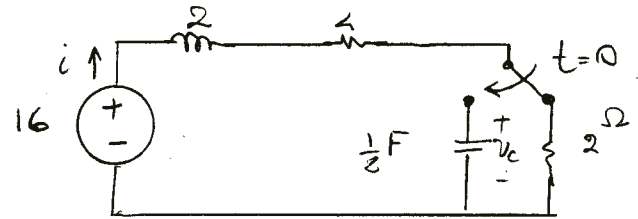
$$S_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2}$$

$$S_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2}$$

$$v_c = K_1 e^{S_1 t} + K_2 e^{S_2 t}$$

Again K_1 & K_2 can be found from I.C. . The waveforms are similar to critically damped case. the Critically damped case, however, reaches steady state conditions the fastest.

Example: Circuit below is in DC steady state for $t < 0^s$.
Find $i(t)$ after the switch has been moved.

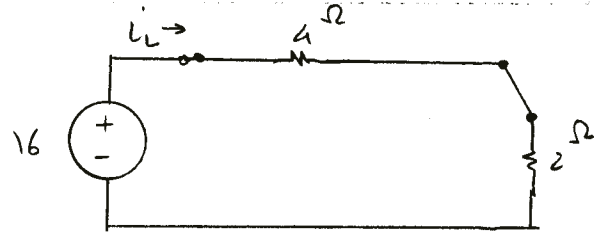


$t < 0$ (DC steady state)

$$v_C = 0$$

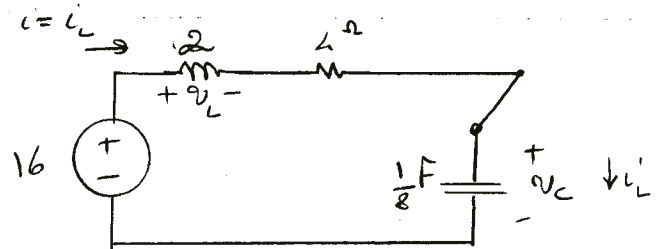
KVL: $i_L = \frac{16}{4} = \frac{8}{3} \text{ A}$

Thus $i_L(t=0^+) = \frac{8}{3} \text{ A}$
 $v_C(t=0^+) = 0$



$t > 0$

KVL: $v_L + 4i_L + v_C - 16 = 0$



Element laws: $v_L = L \frac{di_L}{dt} = 2 \frac{di_L}{dt}$

$$i_C = i_L = C \frac{dv_C}{dt} = \frac{1}{8} \frac{dv_C}{dt}$$

Thus
$$\begin{cases} 2 \frac{di_L}{dt} + 4i_L + v_C = 16 \\ i_L = \frac{1}{8} \frac{dv_C}{dt} \end{cases}$$

Substituting for i_L in the first equation will result in a 2nd order differential equation. Alternatively, substituting for v_C from 1st equation into the 2nd equation will result in a 2nd order differential equation for i_L .

$$8 i_L = \frac{dv_C}{dt} = \frac{d}{dt} \left[16 - 2 \frac{di_L}{dt} - 4i_L \right]$$

$$2 \frac{d^2 i_L}{dt^2} + 4 \frac{di_L}{dt} + 8 i_L = 0$$

$$\frac{di_L}{dt^2} + 2 \frac{di_L}{dt} + 4i_L = 0$$

initial conditions. $i_L(t=0^+) = \frac{8}{3} A$

To find $\frac{di_L}{dt} \Big|_{t=0^+}$, evaluate KVL at $t=$

$$2 \frac{di_L}{dt} \Big|_{t=0^+} + 4i_L(t=0^+) + v_L(t=0^+) = 16$$

$$2 \frac{di_L}{dt} \Big|_{t=0^+} + \frac{32}{3} + 0 = 16 \Rightarrow \frac{di_L}{dt} \Big|_{t=0^+} = \frac{8}{3}$$

Solution (note no forced response). Try $i_L = K e^{st}$

$$K s^2 e^{st} + 2K s e^{st} + 4K e^{st} = 0$$

$$s^2 + 2s + 4 = 0$$

Characteristic Eq.

Note $\alpha=1$, $\omega_o^2=4 \Rightarrow$ underdamped solution ($\omega_d^2=3$)

$$s = -1 \pm \sqrt{1-4} = -1 \pm j\sqrt{3}$$

Thus $i_L = e^{-t} [K_1 \cos(\sqrt{3}t) + K_2 \sin(\sqrt{3}t)]$

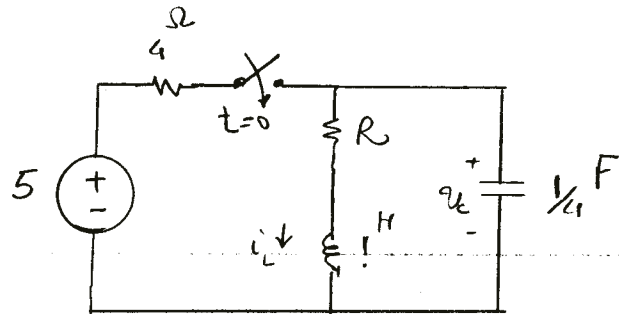
To find K_1 & K_2 , use initial conditions

$$\left\{ \begin{aligned} i_L(t=0^+) &= K_1 = \frac{8}{3} \\ \frac{di_L}{dt} \Big|_{t=0^+} &= -e^{-t} [K_1 \cos(\sqrt{3}t) + K_2 \sin(\sqrt{3}t)] + e^{-t} [-\sqrt{3}K_1 \sin(\sqrt{3}t) + \sqrt{3}K_2 \cos(\sqrt{3}t)] \\ &= -K_1 + \sqrt{3}K_2 = \frac{8}{3} \end{aligned} \right.$$

$$K_1 = \frac{8}{3}, K_2 = \frac{16}{3\sqrt{3}} \Rightarrow i_L(t) = e^{-t} \left[\frac{8}{3} \cos(\sqrt{3}t) + \frac{16}{3\sqrt{3}} \sin(\sqrt{3}t) \right]$$

$$i_L(t) = e^{-t} [2.67 \cos(1.73t) + 3.08 \sin(1.73t)]$$

Example: a) For what value of R , the circuit below is critically damped
 b) find $v_c(t)$ for $t > 0$



for $t \leq 0^-$, circuit is in

DC steady state with $i_L = 0$, $v_c = 0$

Thus $i_L(t = 0^+) = 0$, $v_c(t = 0^+) = 0$

for $t > 0$, use Nodal analysis

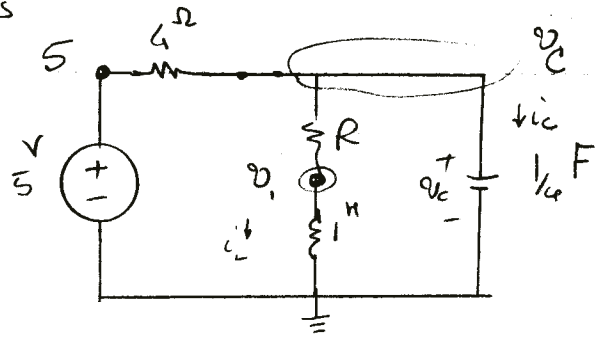
Nodes 1:

$$\frac{v_1 - v_c}{R} + i_L = 0$$

Node C: $i_L + \frac{v_c - v_1}{R} + \frac{v_c - 5}{4} = 0$

Aux: $i_c = C \frac{dv_c}{dt} = \frac{1}{4} \frac{dv_c}{dt}$

$$v_1 = L \frac{di_L}{dt} = \frac{di_L}{dt}$$



Use the two aux. equation for i_c & i_L to substitute in the nodal equations.

Node 1: $v_1 - v_c + R i_L = 0$

Differentiate $\Rightarrow \frac{dv_1}{dt} - \frac{dv_c}{dt} + R \frac{di_L}{dt} = 0 \Rightarrow$ substitute $v_1 = \frac{di_L}{dt}$

$$\frac{dv_1}{dt} - \frac{dv_c}{dt} + R v_1 = 0 \quad \leftarrow$$

Node C: $4R i_c + 4v_c - 4v_1 + R v_c - 5R = 0$

substitute for $i_c \rightarrow R \frac{dv_c}{dt} + (4+R)v_c = 4v_1 = 5R$

$$\begin{cases} \frac{dv_1}{dt} - \frac{dv_c}{dt} + Rv_1 = 0 \\ R \frac{dv_c}{dt} + (4+R)v_c - 4v_1 = 5R \end{cases}$$

In order to reduce this to one 2nd or equation:

$$4v_1 = +R \frac{dv_c}{dt} + (4+R)v_c - 5R$$

$$4 \frac{dv_1}{dt} = +R \frac{d^2v_c}{dt^2} + (4+R) \frac{dv_c}{dt}$$

differentiate
←

$$1^{st} \text{ equation} \Rightarrow 4 \frac{dv_1}{dt} - 4 \frac{dv_c}{dt} + 4Rv_1 = 0$$

$$+ R \frac{d^2v_c}{dt^2} + (4+R) \frac{dv_c}{dt} - 4 \frac{dv_c}{dt} + R \left[+R \frac{dv_c}{dt} + (4+R)v_c - 5R \right] = 0$$

$$R \frac{d^2v_c}{dt^2} + R \frac{dv_c}{dt} + R \left[\right] = 0$$

$$\frac{d^2v_c}{dt^2} + \frac{dv_c}{dt} (1+R) + (4+R)v_c = 5R$$

Substitute $v_c = Ke^{st}$ in the homogenous equation to find the characteristic equation.

$$s^2 + (1+R)s + (4+R) = 0$$

$$\omega_o^2 = 4+R \quad \alpha = \frac{1+R}{2}$$

For system to be critically damped $\alpha^2 = \omega_o^2$

$$4+R = \frac{(1+R)^2}{4} \Rightarrow 16+4R = 1+2R+R^2$$

$$R^2 - 2R - 15 = 0$$

Solution

$$R = 5$$

$$R = -3$$

↑ unphysical

$$\underline{R = 5}$$

thus : $\frac{d^2 v_c}{dt^2} + 6 \frac{dv_c}{dt} + 9v_c = 25$

initial conditions $v_c(t=0^+) = 0$

To find the 2nd initial condition ($\frac{dv_c}{dt}|_{t=0^+}$), we note

Node c $\Rightarrow R \frac{dv_c}{dt} + (4+R)v_c - 4v_i = 5R$

Node i $\Rightarrow v_i = v_c + Ri_L$

Thus (with $R=5$) $\Rightarrow 5 \frac{dv_c}{dt} + 9v_c - 4(v_c + 5i_L) = 25$

evaluate at $t=0^+$ $5 \frac{dv_c}{dt} \Big|_{t=0^+} + 5v_c(t=0^+) - 20i_L(t=0^+) = 25$

$$\frac{dv_c}{dt} \Big|_{t=0^+} = 5$$

Solution: $v_c = v_{c,n} + v_{c,f}$

to find $v_{c,n} \Rightarrow$ characteristic equation: $s^2 + 6s + 9 = 0$, $s_1 = s_2 = -3$

$$v_{c,n} = K_1 e^{-3t} + K_2 t e^{-3t}$$

$v_{c,f}$, using Table on page (88) $\Rightarrow$ trial function $v_{c,f} = A$

$$0 + 6 \times 0 + 9A = 25 \Rightarrow A = \frac{25}{9}$$

Thus $v_c(t) = K_1 e^{-3t} + K_2 t e^{-3t} + \frac{25}{9}$

using initial conditions, we find $K_1 = -\frac{25}{9}$, $K_2 = \frac{10}{3}$

$$v_c(t) = -2.778 e^{-3t} + 3.33 t e^{-3t} + 2.778$$

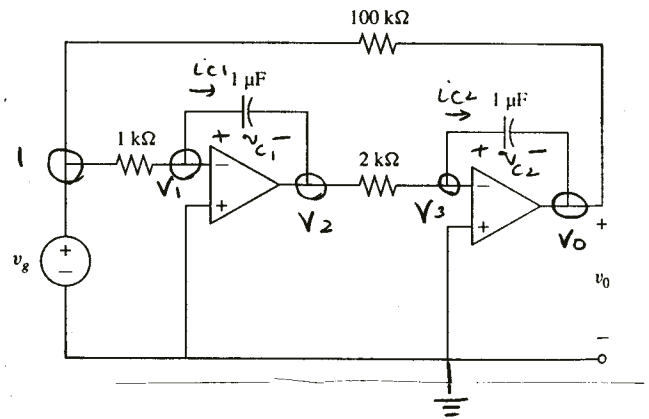
Example: Find step Response.

Step response:

$$t < 0 \quad v_g = 0, \text{ DC steady state}$$

$$v_{c1} = v_{c2} = 0$$

$$t > 0 \quad v_g = 1$$



Use nodal analysis

$$\text{I.C.} \quad v_{c1}(t=0^+) = V_1(t=0^+) - V_2(t=0^+) = 0$$

$$v_{c2}(t=0^+) = V_0(t=0^+) - V_3(t=0^+) = 0$$

$$\text{Node 1:} \quad \frac{V_1 - 1}{10^3} + i_{c1} = 0$$

$$\text{Node 2} \Rightarrow \text{Op Amp output} \Rightarrow v_{d1} = 0 \Rightarrow V_1 = 0$$

$$\text{Node 3} \Rightarrow \frac{V_3 - V_2}{2 \times 10^3} + i_{c2} = 0$$

$$\text{Node 4} \Rightarrow \text{Op Amp output} \Rightarrow v_{d2} = 0 \Rightarrow V_3 = 0$$

$$\text{Aux Eq.} \quad i_{c1} = 10^{-6} \frac{dv_{c1}}{dt} = 10^{-6} \frac{d}{dt} (V_1 - V_2)$$

$$i_{c2} = 10^{-6} \frac{dv_{c2}}{dt} = 10^{-6} \frac{d}{dt} (V_0 - V_3)$$

Thus:

$$\begin{cases} V_1 = 0 \\ V_3 = 0 \\ i_{c1} = +10^{-3} \frac{d}{dt} (-V_2) \\ i_{c2} = 0.5 \times 10^{-3} \frac{d}{dt} (V_0) \end{cases}$$

$$\begin{cases} \frac{dV_2}{dt} = -10^{+3} \\ \frac{dV_0}{dt} = 0.5 \times 10^3 V_2 \end{cases}$$

$$\text{I.C.} \quad V_2(t=0^+) = 0, \quad V_0(t=0^+) = 0$$

Solution:
 ★ General Method.

differentiate the 2nd equation & substitute for $\frac{dV_2}{dt}$

$$\frac{d^2 V_0}{dt^2} = 0.5 \times 10^3 \frac{dV_2}{dt} = -0.5 \times 10^6$$

$$\text{I.C. } V_0(t=0^+) = 0 \quad \left. \frac{dV_0}{dt} \right|_{t=0^+} = 0.5 \times 10^3 V_2(t=0^+) = 0$$

Thus integrating

$$\frac{dV_0}{dt} = -0.5 \times 10^6 t + K_1$$

$$V_0 = -0.25 \times 10^6 t^2 + K_1 t + K_2$$

using the initial conditions $\Rightarrow K_1 = 0, K_2 = 0 \Rightarrow V_0 = -0.25 \times 10^6 t^2$

★ For cascade op Amp circuit, the nodal differential equations usually are in the form that can be directly integrated,

$$\frac{dV_2}{dt} = -10^3 \Rightarrow V_2(t) = -10^3 t + K_1$$

$$V_2(t=0^+) = 0 \Rightarrow K_1 = 0 \Rightarrow V_2(t) = -10^3 t$$

$$\frac{dV_0}{dt} = 0.5 \times 10^3 V_2 = -0.5 \times 10^6 t$$

$$V_0(t) = -0.25 \times 10^6 t^2 + K_2$$

$$V_0(t=0^+) = 0 \Rightarrow K_2 = 0$$

$$V_0(t) = -0.25 \times 10^6 t^2$$

Review of 2^{nd} order Circuit

$$\frac{d^2x}{dt^2} + 2\alpha \frac{dx}{dt} + \omega_0^2 x = f(t) \quad \Rightarrow \quad x = X_n + X_f$$

* need two initial conditions $x(t=t_0)$ & $\frac{dx}{dt}(x=x_0)$

Homogeneous equation: $\frac{d^2x}{dt^2} + 2\alpha \frac{dx}{dt} + \omega_0^2 x = 0$

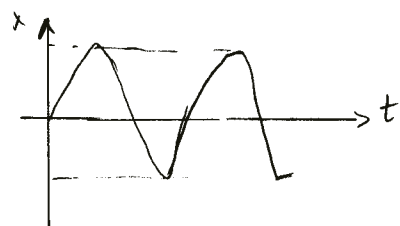
Characteristic equation: $s^2 + 2\alpha s + \omega_0^2 = 0$

$$\begin{cases} s_1 = -\alpha + \sqrt{\alpha^2 - \omega_0^2} \\ s_2 = -\alpha - \sqrt{\alpha^2 - \omega_0^2} \end{cases}$$

ω_0 : Undamped natural frequency
 $\omega_d = \sqrt{\omega_0^2 - \alpha^2}$ damped natural frequency
 $\frac{\alpha}{\omega_0}$: damping ratio

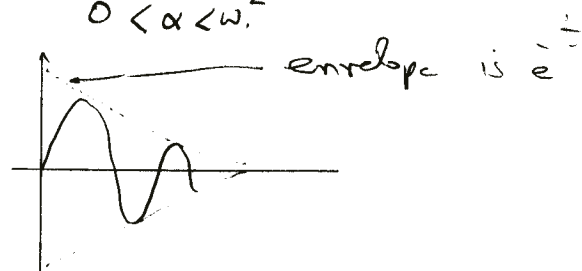
Undamped (harmonic Oscillator)

$$\alpha = 0$$



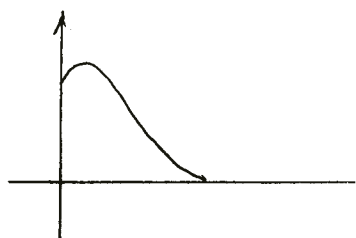
Underdamped

$$0 < \alpha < \omega_0$$



Critically damped ($\alpha = \omega_0$)

* Fastest to steady state



Overdamped

$$\omega_0^2 < \alpha$$

