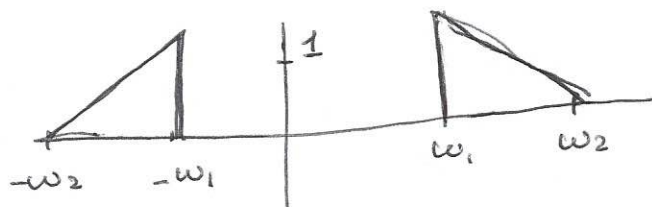
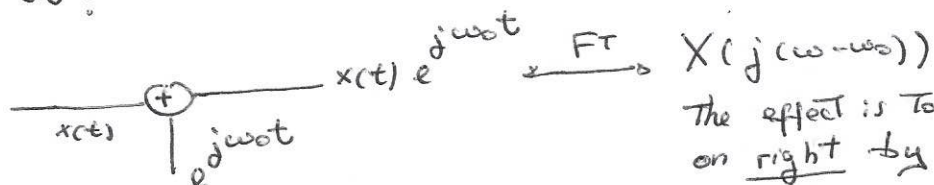


PROBLEM SETS

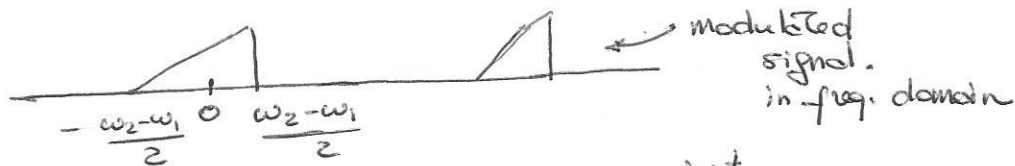
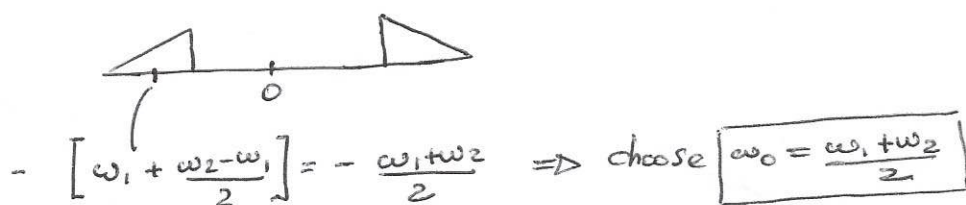


min sampling rate is $\geq 2w_2$
 however, there is a lot of "white space"
 what can we do?

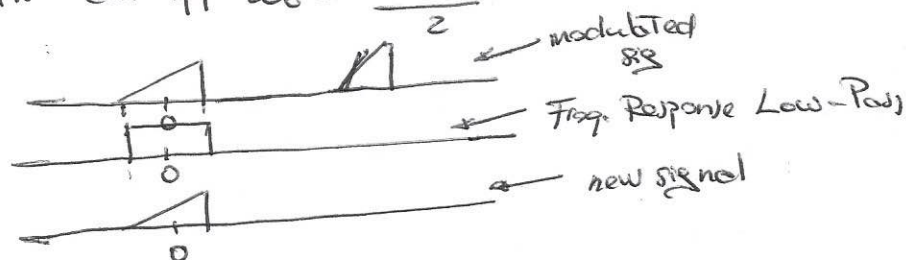
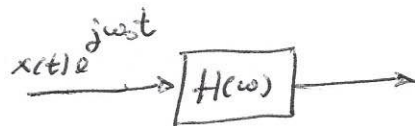
① Modulate



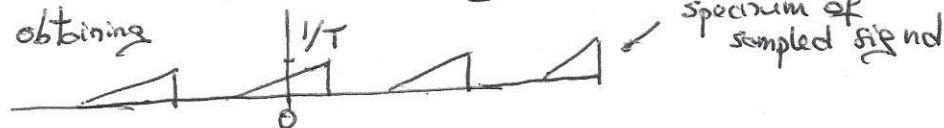
The effect is to shift spectrum
 on right by ω_0 in freq.



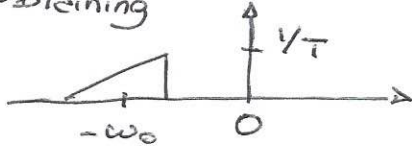
② Low Pass with cut-off $\omega_0' = \frac{\omega_2 - \omega_1}{2}$



③ Sample new signal with freq $\geq \frac{\omega_2 - \omega_1}{2}$ obtaining



- ④ To recover original signal first LOW-PASS again with cut-off $\frac{\omega_2 - \omega_1}{2}$ then modulate by multiply by $e^{-j\omega_0 t}$ $\omega_0 = \frac{\omega_1 + \omega_2}{2}$ obtaining



- ⑤ Then To obtain original signal either multiply by 2 and Take real part:

$$\text{Re}[x(t)] = \frac{1}{2} [x(t) + x^*(t)] \xrightarrow{\text{FT}} \frac{1}{2} X(j\omega) + \frac{1}{2} X^*(j\omega)$$

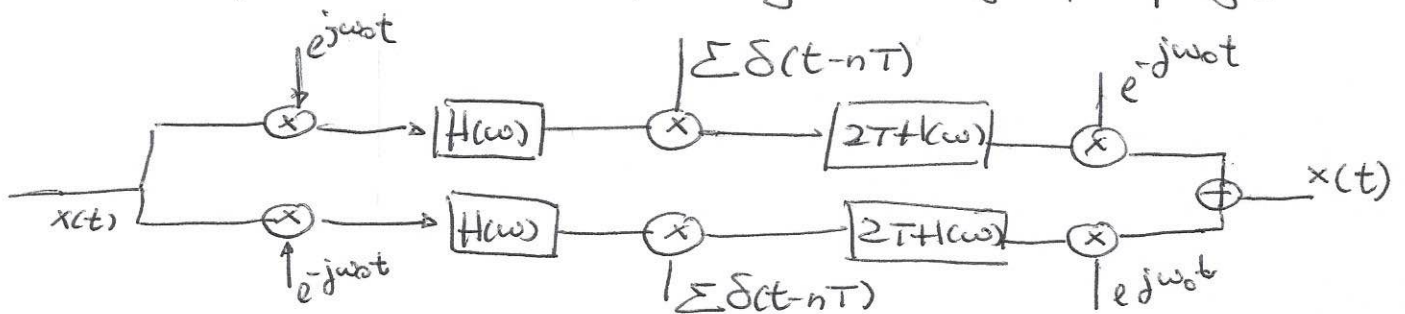
The absolute value is

$$\frac{1}{2} |X(j\omega) + X^*(j\omega)|$$

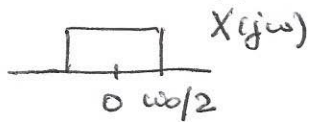
if support of $X(j\omega)$ does not contain origin we have

$$\begin{aligned} & \frac{1}{2} |X(j\omega)| + \frac{1}{2} |X(j\omega)|^* \\ &= \frac{1}{2} |X(j\omega)| + \frac{1}{2} |X(-j\omega)| \end{aligned}$$

Alternatively redo the same steps to get the right part of signal



Determine Nyquist sampling rate of the following signals

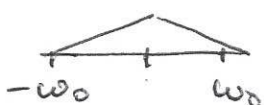


$$\text{Nyquist rate} = \omega_0$$

$$x(t) + x(t-1) \longleftrightarrow X(j\omega) + X(j\omega)e^{-j\omega} \Rightarrow \text{Nyquist rate} = \omega_0$$

$$\frac{dx(t)}{dt} \longleftrightarrow j\omega X(j\omega) \Rightarrow \text{Nyquist rate} = \omega_0$$

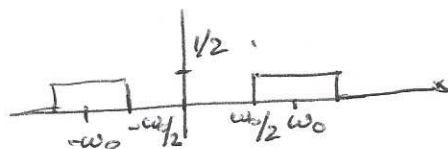
$$x^2(t) \longleftrightarrow \frac{1}{2\pi} X \circledast X(j\omega)$$



support in freq is $2\omega_0 \Rightarrow \text{Nyquist rate} = 2\omega_0$

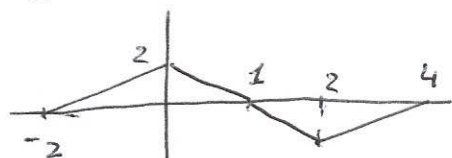
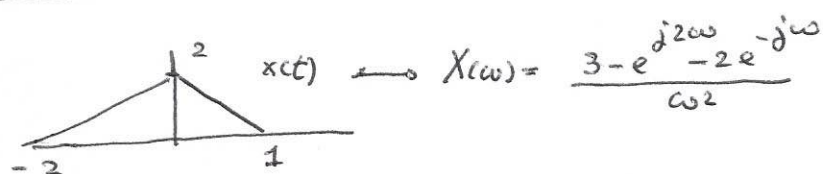
consider $x(t) \cos(\omega_0 t) \longleftrightarrow \frac{1}{2} X(\omega - \omega_0) + \frac{1}{2} X(\omega + \omega_0)$

$$\frac{x(t) e^{j\omega_0 t}}{2} + \frac{x(t) e^{-j\omega_0 t}}{2}$$



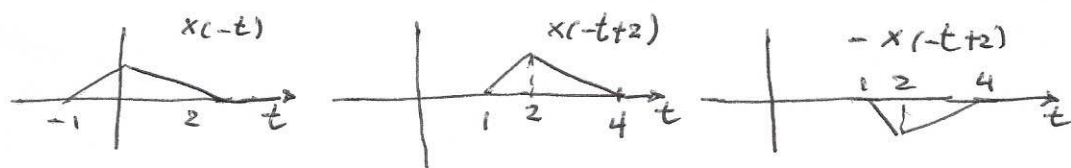
New Nyquist rate $\boxed{3\omega_0}$

MT2 P3



$$y(t) = x(t) - x(t-2)$$

since



Now There was a mistake in the solution

$$x(t-2) \longleftrightarrow X(j\omega) e^{-2j\omega} \quad (1)$$

$$x(-t) \longleftrightarrow X(-j\omega) \quad (2)$$

$$x(-t+2) \longleftrightarrow X(-j\omega) e^{2j\omega} \quad (3)$$

However the above is wrong. To see this, let's apply the definition directly

$$\int_{-\infty}^{\infty} x(-t+2) e^{-j\omega t} dt = \int_{-\infty}^{\infty} x(-z) e^{-j\omega(z+2)} dz = e^{-2j\omega} \int_{-\infty}^{\infty} x(-z) e^{j\omega z} dz = \boxed{X(-j\omega) e^{-2j\omega}}$$

call $t-2=z$

so the correct result is $X(-j\omega) e^{-2j\omega}$

The problem occurs in the third line (3) $x(-(t-2)) \longleftrightarrow X(-j\omega) e^{2j\omega}$ This is incorrect because it is incorrectly applying the shifting property (1) which could be valid to $x(+t+2) \longleftrightarrow X(j\omega) e^{+2j\omega}$ namely when the variable is $+t$. In our case, however, the variable is $-t$ and we have

$$x(-(t-2)) \longleftrightarrow e^{-2j\omega} X(-j\omega)$$

where we are correctly applying the scaling property

$$x(at) \longleftrightarrow \frac{1}{|a|} X(aj\omega)$$

where $a = -1$ and $t = t-2$

ω is the transformed var of $t-2$

$$x(t-2) \longleftrightarrow X(j\omega) e^{-2j\omega}$$

now we can continue with the solution and we have

$$Y(j\omega) = X(j\omega) - X(j\omega) e^{-2j\omega}$$

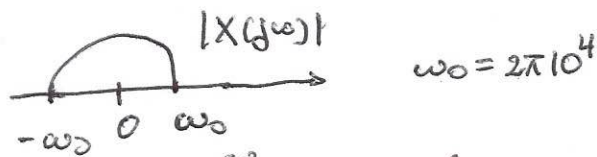
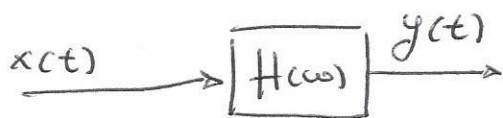
$$= \frac{3 - e^{j2\omega} - 2e^{-j\omega}}{\omega^2} - \frac{3 - e^{-2j\omega} - 2e^{j\omega}}{\omega^2} e^{-2j\omega}$$

$$= \frac{3 - e^{j2\omega} - 2e^{-j\omega} - 3e^{-2j\omega} + e^{-4j\omega} + 2e^{j\omega}}{\omega^2}$$

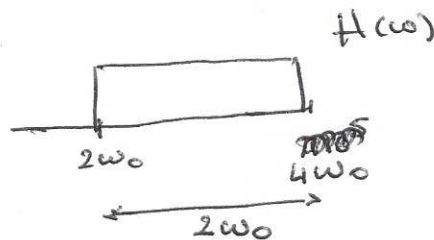
$$= \frac{3 - e^{j2\omega} - 3e^{-2j\omega} + e^{-4j\omega}}{\omega^2}$$

MODULATION PROBLEM

Assume you want to send a signal $x_0(t)$ through a LTI system and recover it at the receiver

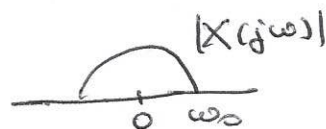
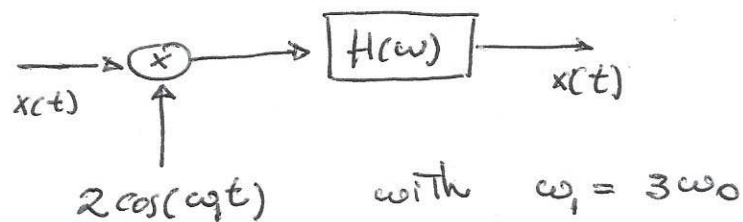


$$H(\omega) = \begin{cases} 1 & \text{for } 2\omega_0 \leq \omega \leq 4\omega_0 \\ 0 & \text{otherwise} \end{cases} \Rightarrow$$

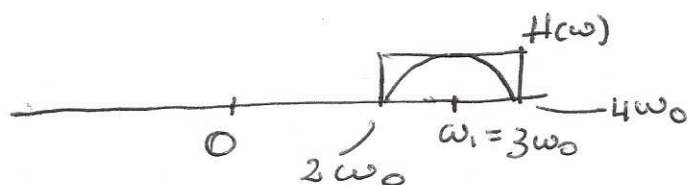


- ① Check if additional processing is needed
 YES because band-pass filter and signal is out-of-band $\omega_0 < 2\omega_0$

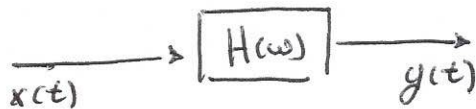
- ② If needed what processing can you design?



$$|X(j\omega) \cos(\omega_1 t)| = \frac{1}{2} X(j(\omega + \omega_1)) + \frac{1}{2} X(j(\omega - \omega_1))$$



Consider an LTI system



Let $h(t) = u(t)$ step function at the origin
determine $y(t)$ if $x(t) = \frac{d}{dt} f(t)$ for some ~~known~~ signal $f(t)$

We proceed in frequency domain $x(t) \longleftrightarrow X(j\omega)$ $f(t) \longleftrightarrow F(j\omega)$
First we determine $H(\omega) X(j\omega)$

$$= j\omega F(j\omega) H(\omega)$$

$$= j\omega H(\omega) F(j\omega)$$

$$= Y(j\omega)$$

Now we notice $j\omega F(j\omega) \longleftrightarrow \frac{d}{dt} h(t) = \frac{d}{dt} u(t) = \delta(t)$

$$FT(\delta(t)) = 1$$

so that we have

$$j\omega H(j\omega) = 1$$

$$Y(j\omega) = F(j\omega)$$

$$\boxed{y(t) = f(t)}$$