

DIRAC'S δ -function

In last lecture we have introduced the δ -function as the limiting function of the sinc as this becomes an impulse centered at the origin.

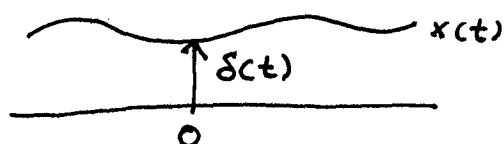
In this lecture we take a closer look.

Let's first give a formal definition and then we give some intuition for it.

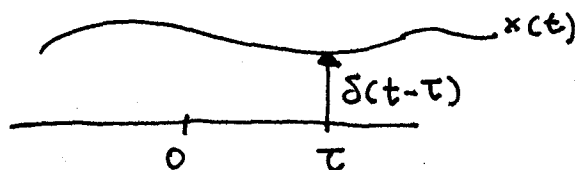
DEFINE $\delta(t)$ a function such that for any continuous signal $x(t)$, we have:

$$\int_{t_1}^{t_2} x(t) \delta(t) dt = \begin{cases} x(0) & \text{if } 0 \in [t_1, t_2] \\ 0 & \text{if } 0 \notin [t_1, t_2] \end{cases}$$

and we indicate it graphically with an arrow (indicating the "spike" of the impulse).



$$\int_{-\infty}^{+\infty} x(t) \delta(t) dt = x(0)$$



$$\int_{-\infty}^{+\infty} x(t) \delta(t-\tau) dt = x(\tau)$$

We also have another important property.

CONVOLUTION PROPERTY of the δ -function

$$\int_{-\infty}^{+\infty} x(\tau) \delta(t-\tau) d\tau = x(t)$$

the integral $\int_{-\infty}^{+\infty} f(\tau) g(t-\tau) d\tau = f \otimes g(t)$

is called the convolution integral, so the property above says that convolution ~~of~~ of the signal x with the δ -function is the signal $x(t)$ itself. In other words, convolution with the δ -function is equivalent to letting the signal pass-through undisturbed.

Let's prove the property:

$$\int_{-\infty}^{+\infty} x(t) \delta(t-\tau) dt = x(\tau)$$

call $t \rightarrow \tau$ $\tau \rightarrow t$, we have

$$\int_{-\infty}^{+\infty} x(\tau) \delta(\tau-t) d\tau = x(t)$$

But we also have that $\delta(t)$ is an even function, so

$\delta(t-\tau) = \delta(\tau-t)$ and we finally have:

$$\int_{-\infty}^{+\infty} x(\tau) \delta(t-\tau) d\tau = x(t)$$

The fact that $\delta(t)$ is even follows by the following

SCALING PROPERTY

$$\delta(at) = \frac{1}{|a|} \delta(t)$$

which implies $\delta(t) = \delta(-t)$

Let's prove the scaling property:

$$\begin{aligned} \int_{-\infty}^{\infty} x(t) \delta(at) dt & \stackrel{\substack{\text{call } t' = at \\ dt' = a dt}}{=} \int x\left(\frac{t'}{a}\right) \delta(t') \frac{dt'}{a} = \begin{cases} \boxed{a > 0} \int_{-\infty}^{\infty} \frac{1}{a} x\left(\frac{t'}{a}\right) \delta(t') dt' \\ \boxed{a < 0} \int_{\infty}^{-\infty} \frac{1}{a} x\left(\frac{t'}{a}\right) \delta(t') dt' \end{cases} \\ & = \frac{1}{|a|} \int_{-\infty}^{\infty} x\left(\frac{t'}{a}\right) \delta(t') dt' = \frac{1}{|a|} x(0) \end{aligned}$$

so now the property follows by the definition of δ -function.

We have proven the convolution property of the δ -function: convolution of a signal by $\delta(t)$ is the signal itself. Let's see what does this mean in the frequency domain:

$$x \otimes h(t) \longleftrightarrow X(j\omega) \cdot H(j\omega)$$

The convolution integral in the time-domain corresponds to a simple multiplication in the frequency domain. So, by this property, we have:

$$FT(x \otimes \delta(t)) = X(j\omega) \cdot FT(\delta(t)) = X(j\omega) \cdot 1$$

$$\text{since: } FT(\delta(t)) = \int_{-\infty}^{\infty} \delta(t) e^{-j\omega t} dt = e^0 = 1$$

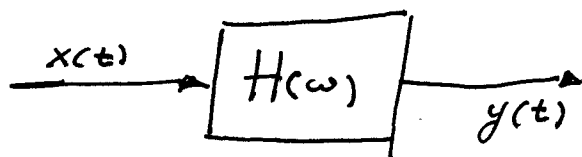
Summarizing, we have:

convolution in time domain
corresponds to multiplication
in freq. domain

The FT of $\delta(t)$ is a
constant

$\Rightarrow$ convolution in time-domain with $\delta(t)$ corresponds to multiplication by a constant 1 in the frequency domain.

Now, a simple exercise



Let $x(t) = \delta(t)$ and let's solve this system

$$FT(x(t)) = 1$$

$$Y(j\omega) = 1 \cdot H(j\omega)$$

$$y(t) = FT^{-1}[H(j\omega)]$$

so the inverse FT of the function $H(j\omega)$ is the response of the system to the input $\delta(t)$

But by the convolution property, we also have:

$$FT^{-1}[1 \cdot H(j\omega)] = \delta(t) * h(t) = y(t)$$

so the response of the system is given by the convolution of $\delta(t)$ with $h(t)$, the inverse FT of $H(j\omega)$.

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graph LR
    delta_t["delta(t)"] --> h_t["h(t)"]
    h_t --> y_t["y(t)"]
  
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$$y(t) = \int_{-\infty}^{+\infty} h(t) \delta(t-\tau) d\tau = h(t)$$

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graph LR
    1 --> H_jw["H(jw)"]
    H_jw --> y_t["y(t)"]
  
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$$y(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} H(j\omega) e^{j\omega t} d\omega = h(t)$$

So we have found that our "favorite function" $H(\omega)$ that we have used many times to study linear systems and to solve problem sets and which was introduced as $H(\omega)$

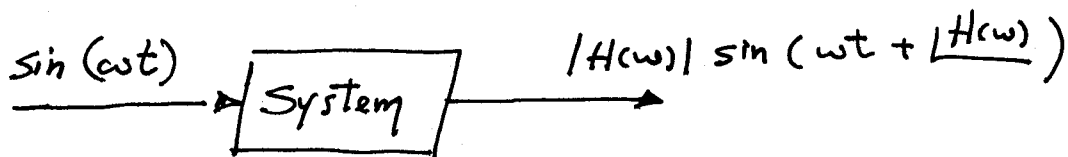
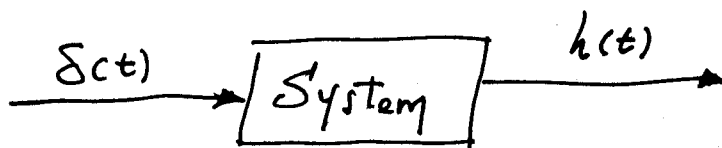
"The response of the system to ~~an~~ ^{an} input at a single frequency ω " (1)

is also the Fourier Transform of $h(t)$

"the response of the system to an impulse $\delta(t)$ " (2)

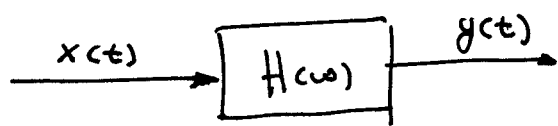
Note ~~the~~ ^{an} important differences:

- (1) "response" is intended as multiplying a single input frequency (sinusoid) by $|H(\omega)|$ and phase shifting by $\angle H(\omega)$
- (2) "response" is intended as the actual output we observe if we place an impulse $\delta(t)$ as input to the system.



$$H(\omega) = \int_{-\infty}^{+\infty} h(t) e^{-j\omega t} dt$$

What we do know from previous lectures:



$$y(t) = \mathcal{F}^{-1} [X(j\omega) \cdot H(j\omega)] = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau = x \otimes h(t)$$

convolution property

So we have an alternative way of computing the output of the system directly in time domain by solving the convolution integral of the input $x(t)$ with the impulse response $h(t)$

INTUITIVE INTERPRETATION

$$\begin{aligned} y(t) &= \mathcal{F}^{-1} [X(j\omega) \cdot H(j\omega)] = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) H(j\omega) e^{j\omega t} d\omega \\ &= \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\omega) \cdot |H(j\omega)| e^{j\omega t + \angle H(j\omega)} d\omega \end{aligned}$$

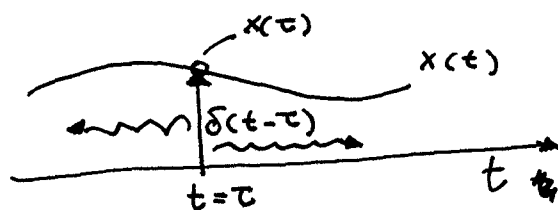
We have given an interpretation of this formula in previous lectures using the superposition principle: we are summing the responses at all frequencies ω , each weighted by the absolute value $|H(j\omega)|$ and phase shifted by the phase $\angle H(j\omega)$. Remember the correspondence with the Fourier Series in which the role of the coefficients c_n is replaced here by $X(j\omega)$.

In other words the signal $x(t)$ has a spectrum of frequencies $X(j\omega)$ and we are summing the single responses to each one of them using the integral representation.

Now, what is the intuitive interpretation of the convolution integral?

Remember that:

$$x(t) = \int_{-\infty}^{+\infty} x(\tau) \delta(t-\tau) d\tau$$



This says that $x(t)$ can be seen as a continuous sum of all of its values $x(\tau)$ obtained by "sweeping" the δ -function along the time-axis.

We have something similar by writing the output $y(t)$

$$y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$$

Again we "sweep" along the time-axis but this time instead of the δ -function we use its response $h(t)$.

In other words, $x(t)$ is the ~~sum~~ (continuous) sum of δ -functions each weighted by the coefficient $x(\tau)$.

Similarly $y(t)$ is the (continuous) sum of the response of the δ -function, each weighted by the same coefficient $x(\tau)$.

Again we see a manifestation of the superposition principle!

Finally, let's prove the convolution property:

$$\begin{aligned}
 \text{FT} \left(\int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau \right) &= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} x(\tau) h(t-\tau) e^{-j\omega t} dt d\tau \\
 &= \int_{-\infty}^{\infty} x(\tau) \left(\int_{-\infty}^{\infty} h(t-\tau) e^{-j\omega t} dt \right) d\tau = \int_{-\infty}^{\infty} x(\tau) e^{-j\omega \tau} H(j\omega) d\tau \\
 &\quad \swarrow \text{shifting property} \\
 &= H(j\omega) \int_{-\infty}^{\infty} x(\tau) e^{-j\omega \tau} d\tau = H(j\omega) \cdot X(j\omega)
 \end{aligned}$$