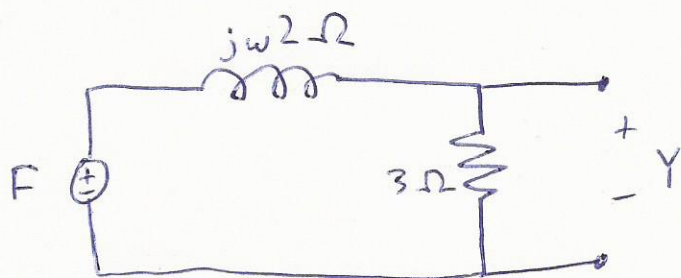


①. Phasorize circuit:



use voltage division:

$$Y = \frac{3}{3 + j\omega 2} F \rightarrow \frac{Y}{F} = H(\omega) = \frac{3}{3 + j\omega 2}$$

multi-frequency input: (0, 2, 4)

$$H(0) = 1$$

$$H(2) = \frac{3}{3 + 4j} = \frac{3}{5} \angle -53.13^\circ$$

$$H(4) = \frac{3}{3 + 8j} = 0.35 \angle -69.44^\circ$$

OK to leave as fractions
or $\tan(b/a)$

$$\Rightarrow y(t) = |H(0)| \cdot 5 + |H(2)| \sin(2t + \angle H(2)) + |H(4)| \cos(4t + \angle H(4))$$

$$y(t) = 5 + 0.6 \sin(2t - 53.13^\circ) + 0.35 \cos(4t - 69.44^\circ)$$

OK as
fractions
or $\tan(b/a)$

$$(2) \quad H(\omega) = 10^6 \frac{(j\omega)^2 + j\omega}{(j\omega+10)(j\omega+10)(j\omega+100)} = 100 \frac{j\omega(j\omega+1)}{\left(\frac{j\omega}{10}+1\right)^2 \left(\frac{j\omega}{100}+1\right)}$$

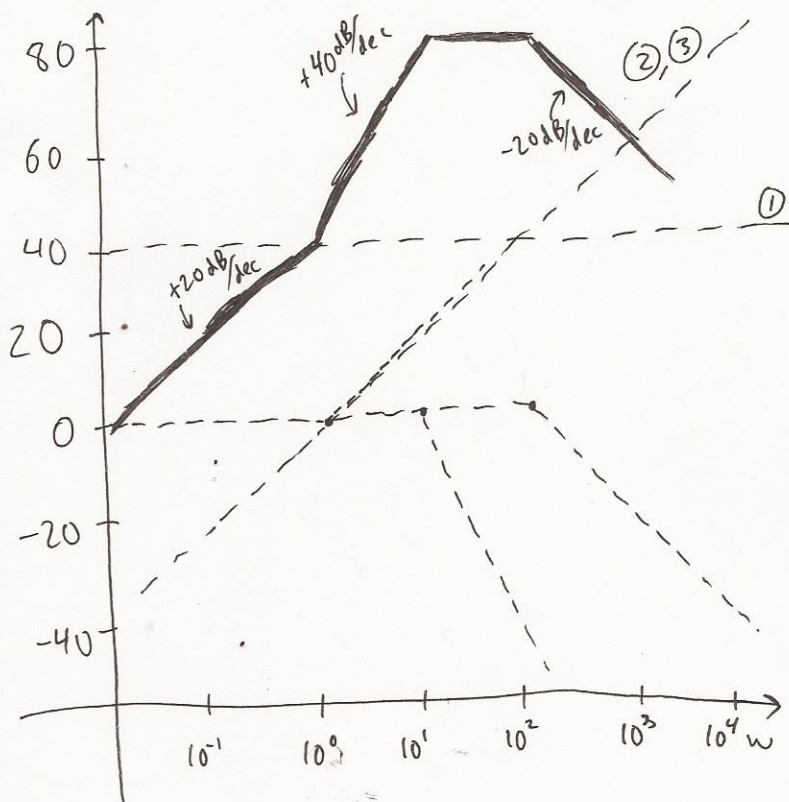
Components:

- ① Constant of 100
- ② zero $[j\omega]$
- ③ zero $[j\omega+1]$
- ④ pole $\left[\frac{j\omega}{100}+1\right]^{-1}$
- ⑤ double-pole $\left[\frac{j\omega}{10}+1\right]^{-2}$

Bode Plot:

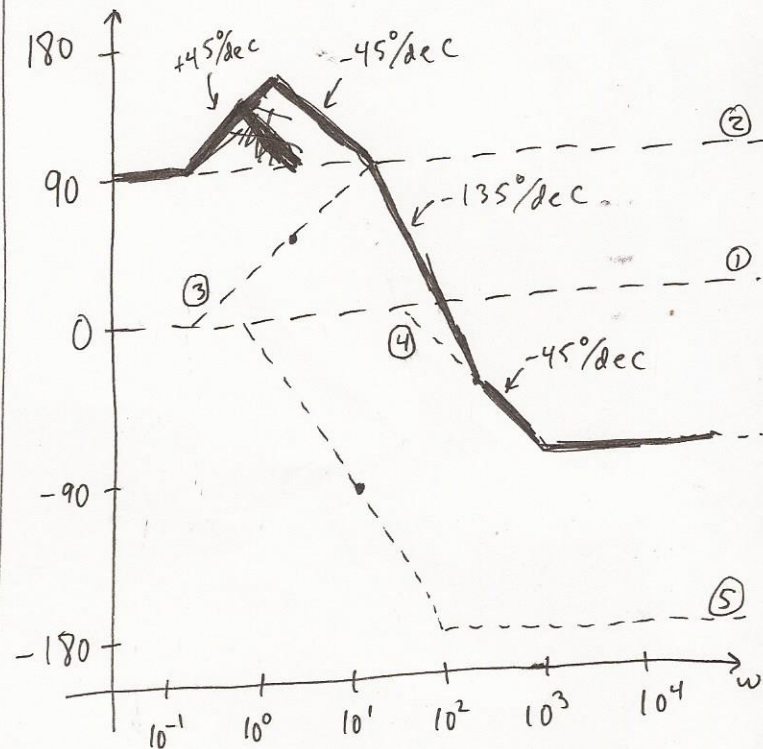
Magnitude:

[dB]



Phase:

[°]



3. (a) $T_0 = 4, \omega_0 = \frac{\pi}{2}$

$$X_{1,n} = \frac{1}{4} \int_0^4 x_1(t) e^{-jn(\frac{\pi}{2})t} dt$$

$$X_{1,n} = \frac{1}{4} \left[\int_0^1 e^{-jn\frac{\pi}{2}t} dt + \int_1^2 e^{-jn\frac{\pi}{2}t} dt + \int_2^4 0 dt \right]$$

$$X_{1,n} = \frac{1}{4} \left[\frac{e^{-jn\frac{\pi}{2}t}}{-jn\frac{\pi}{2}} \Big|_0^1 - \frac{e^{-jn\frac{\pi}{2}t}}{-jn\frac{\pi}{2}} \Big|_1^2 \right] = \frac{e^{-jn\frac{\pi}{2}} - 1 - e^{-jn\pi} + e^{-jn\frac{\pi}{2}}}{-jn2\pi} = \frac{1 + e^{-jn\pi} - 2e^{-jn\frac{\pi}{2}}}{2n\pi j}$$

(further simplification optional)

(b) This function $x_2(t)$ is related to $x_1(t)$:

$$\frac{dx_2(t-t_0)}{dt} = x_1(t), \quad t_0 = -2$$

So, use properties: $X_{1,n} = jn\frac{\pi}{2} X_{2,n}^{\text{no shift}} \rightarrow X_{2,n}^{\text{no shift}} = \frac{X_{1,n}}{jn\frac{\pi}{2}}$

~~$X_{2,n} = X_{2,n}^{\text{no shift}}$~~ $x_2(t) = X_2^{\text{no shift}}(t - t_0), \quad t_0 = -2$

$$\Rightarrow X_{2,n} = X_{2,n}^{\text{no shift}} e^{-jn\frac{\pi}{2}(-2)} \Rightarrow X_{2,n} = \frac{X_{1,n}}{jn\frac{\pi}{2}} e^{jn\pi} \quad (\text{plugging in } X_{1,n} \text{ optional})$$

(c) This function $x_3(t)$ is the sum $x_1(t) + x_2(t) = x_3(t)$

So, use properties:

$$X_{3,n} = X_{1,n} + X_{2,n} \quad (\text{plugging in } X_{1,n} \text{ and } X_{2,n} \text{ optional})$$

(4)

$$a_k = \begin{cases} 2, & k=0 \\ j\left(\frac{1}{2}\right)^{|k|}, & k \neq 0 \end{cases}$$

(problem 3.26 in book)

(a) If $x(t)$ is real, then $x(t) = x^*(t)$

This implies that for $x(t)$ real, $a_k = a_{-k}^*$

Since this is not true, $x(t)$ is not real

(b) If $x(t)$ is even, then $x(t) = x(-t)$, and $a_k = a_{-k}$

Since this is true, $x(t)$ is even

(c)

$$g(t) = \frac{dx(t)}{dt} \xleftrightarrow{\text{FS.}} b_k = jk \frac{2\pi}{T_0} a_k$$

$$\Rightarrow b_k = \begin{cases} 0, & k=0 \\ -k \frac{2\pi}{T_0} \left(\frac{1}{2}\right)^{|k|}, & k \neq 0 \end{cases} \quad \begin{matrix} \swarrow \\ u_0 = 0, T \rightarrow \infty \end{matrix}$$

b_k is not even $\Rightarrow \frac{dx(t)}{dt}$ is not even