## Vector calculus in (almost) one page.

You should know the following operators and formulas. We use Cartesian coordinates $\mathbf{r}=\mathbf{x}=(x, y, z)=\left(x_{1}, x_{2}, x_{3}\right)$. Write the vectors $\mathbf{a}$ and $\mathbf{b}$ as $\mathbf{a}=\left(a_{1}, a_{2}, a_{3}\right)$ and $\mathbf{b}=$ $\left(b_{1}, b_{2}, b_{3}\right) ; f(\mathbf{x})$ is a scalar function of $\mathbf{x}$ and $\mathbf{u}(\mathbf{x})=\left(u_{1}, u_{2}, u_{3}\right)$ is a vector function of $\mathbf{x}$.
Dot product: $\mathbf{a} \cdot \mathbf{b}=a_{1} b_{1}+a_{2} b_{2}+a_{3} b_{3}$. The dot product of two vectors is a scalar.
Cross product: $\mathbf{a} \times \mathbf{b}=\left(a_{2} b_{3}-a_{3} b_{2}, a_{3} b_{1}-a_{1} b_{3}, a_{1} b_{2}-a_{2} b_{1}\right)$. The cross product of two vectors is a vector.

## Gradient:

$$
\nabla f=\left(\frac{\partial f}{\partial x_{1}}, \frac{\partial f}{\partial x_{2}}, \frac{\partial f}{\partial x_{3}}\right)
$$

The gradient of a scalar function is a vector.
Divergence:

$$
\nabla \cdot \mathbf{u}=\frac{\partial u_{1}}{\partial x_{1}}+\frac{\partial u_{2}}{\partial x_{2}}+\frac{\partial u_{3}}{\partial x_{3}} .
$$

The divergence of a vector function is a scalar.

## Curl:

$$
\nabla \times \mathbf{u}=\left(\frac{\partial u_{3}}{\partial x_{2}}-\frac{\partial u_{2}}{\partial x_{3}}, \frac{\partial u_{1}}{\partial x_{3}}-\frac{\partial u_{3}}{\partial x_{1}}, \frac{\partial u_{2}}{\partial x_{1}}-\frac{\partial u_{1}}{\partial x_{2}}\right) .
$$

The curl of a vector function is a vector.
Differentials:

$$
\mathrm{d} f=\frac{\partial f}{\partial x_{1}} \mathrm{~d} x_{1}+\frac{\partial f}{\partial x_{2}} \mathrm{~d} x_{2}+\frac{\partial f}{\partial x_{3}} \mathrm{~d} x_{3} .
$$

## Divergence theorem:

$$
\int_{V} \nabla \cdot \mathbf{u} \mathrm{~d} V=\int_{S} \mathbf{u} \cdot \mathbf{n} \mathrm{~d} S
$$

where $\mathbf{n}$ is the unit vector oriented outward from the volume $V$.
Stokes' theorem:

$$
\int_{S} \nabla \times \mathbf{u} \cdot \mathbf{n} \mathrm{d} S=\int_{C} \mathbf{u} \cdot \mathrm{~d} \mathbf{l}
$$

where $C$ is any curve bounding the open surface $S$.
Show that given $\mathbf{a}=(2 x, 3 x y, 0), \mathbf{b}=(2, x, 0)$ and $f=3 x y^{2}, \mathbf{a} \cdot \mathbf{b}=4 x+3 x^{2} y, \nabla \cdot \mathbf{a}=$ $2+3 x, \mathbf{a} \times \mathbf{b}=\left(0,0,2 x^{2}-6 x y\right), \nabla \times \mathbf{a}=(0,0,3 y), \nabla f=\left(3 y^{2}, 6 x y, 0\right), \nabla \times f=$ absurd.

Suffices and the summation convention: The right way to do vector calculus is using suffices. The vector a is written as $a_{i}$ and repeated indices are summed over. The above operators become

$$
\mathbf{a} \cdot \mathbf{b}=a_{i} b_{i} ; \quad[\mathbf{a} \times \mathbf{b}]_{i}=\epsilon_{i j k} a_{j} b_{k}
$$

where $\epsilon_{i j k}=1$ if $(i, j, k)$ are an even permutation of $(1,2,3),-1$ if they are an odd permutation and 0 otherwise.
The Kronecker delta is defined by $\delta_{i j}=1$ if $i=j$ and 0 otherwise. Note that

$$
\frac{\partial x_{i}}{\partial x_{j}}=\delta_{i j}
$$

Treating the gradient operator as the vector $\nabla$, which is $\partial_{i}$ in suffix notation, the other equations become

$$
[\nabla f]_{i}=\frac{\partial f}{\partial x_{i}} ; \quad \nabla \cdot \mathbf{u}=\frac{\partial u_{i}}{\partial x_{i}} ; \quad[\nabla \times \mathbf{u}]_{i}=\epsilon_{i j k} \frac{\partial u_{k}}{\partial x_{j}} ; \quad \mathrm{d} P=\frac{\partial P}{\partial x_{i}} \mathrm{~d} x_{i} .
$$

This is the only way to do tensors, which have two or more free suffices.
Show using suffices that $\nabla \times \nabla f=\mathbf{0}, \nabla \cdot(\nabla \times \mathbf{u})=0, \delta_{i i}=3$ in 3 dimensions. Compute using suffices $\mathbf{a} \times(\mathbf{b} \times \mathbf{b}), \nabla \times(\nabla \times \mathbf{u})$.

