http://web.eng.ucsd.edu/~sgls/MAE210A_2018

Final Solutions

1 Use $\partial x_i/\partial x_j = \delta_{ij}$. Incompressibility:

$$\frac{\partial u_i}{\partial x_i} = a_{ii} = 0.$$

Irrotationality:

$$\epsilon_{ijk} \frac{\partial}{\partial x_i} a_{kl} x_l = \epsilon_{ijk} a_{kj} = 0.$$

One can either multiply by ϵ_{pqi} or write out in suffices to find $a_{ij} = a_{ji}$. This means the matrix with elements a_{ij} is symmetric. In class, we saw that any flow can be decomposed locally into an antisymmetric part relate to vorticity and a symmetric part related to strain. If the flow is irrotational, the vorticity vanishes and the velocity gradient tensor is symmetric, i.e. $a_{ij} = a_{ji}$. The velocity potential is then $\phi = \frac{1}{2}a_{ij}x_ix_j$ as can be checked.

2 Particle path: solve

$$\frac{\mathrm{d}x}{\mathrm{d}t} = (t + \cos t)y, \qquad \frac{\mathrm{d}y}{\mathrm{d}t} = 0,, \qquad \frac{\mathrm{d}z}{\mathrm{d}t} = -z.$$

The second equation shows that *y* is constant. Using the initial conditions one obtains

$$x(t) = \frac{t^2}{2} + \sin t + 1,$$
 $y(t) = 1,$ $z(t) = e^{-t}.$

Streaklines: solve the particle path equations with initial position (1,1,1) at $t=t_*$, giving

$$x(t,t_*) = \frac{t^2}{2} + \sin t - \frac{t_*^2}{2} - \sin t_* + 1, \qquad y(t,t_*) = 1, \qquad z(t,t_*) = e^{t_* - t}.$$

At $t = \pi$, these give

$$x(t_*) = \frac{\pi^2}{2} - \frac{t_*^2}{2} - \sin t_* + 1, \qquad y(t_*) = 1, \qquad z(t_*) = e^{t_* - \pi}$$

for $0 \le t \le \pi$. Streamlines at t = 0: solve

$$\frac{\mathrm{d}x}{y} = \frac{\mathrm{d}y}{0} = -\frac{\mathrm{d}z}{z} = \mathrm{d}s.$$

This gives $y = y_0$, $x = y_0 s + x_0$ and $z = e^{-s} z_0$ with s = 0 corresponding to the point (x_0, y_0, z_0) . This can also be written as

$$y = y_0$$
, $z = z_0 e^{-(x-x_0)/y_0}$.

3 The upper surface is at z and has velocity v. The exit is at 0 and has velocity v_0 . By mass conservation we have

$$\pi h(z)^2 v = \pi h(0)^2 v_0.$$

Apply Bernoulli's equation on a streamline from the upper surface to the outlet. Assume that at the outlet the flow comes out as a constant-diameter jet so that the pressure there is atmospheric. Then we have

$$gz + \frac{1}{2}v^2 = \frac{1}{2}v_0^2.$$

Eliminate v_0 from these two equations:

$$gz + \frac{1}{2}v^2 = \frac{1}{2}v^2 \frac{h(z)^4}{h(0)^4}.$$

We require v to be constant in time, so this is not an ordinary differential equation but just an algebraic relation. The profile h(z) is given by

$$h(z) = h(0) \left(1 + \frac{2gz}{v^2} \right)^{1/4}.$$

4 For fully-developed flow, $\partial_x = \partial_\theta = 0$. The momentum equation reduces to

$$0 = \frac{1}{r} \frac{\mathrm{d}}{\mathrm{d}r} \left(r \frac{\mathrm{d}u}{\mathrm{d}r} \right),$$

where u is the velocity in the x-direction. The solution is $u = A + B \log r$. The boundary conditions give

$$u = U \frac{\log(r/b)}{\log(a/b)}.$$

The volume flux is

$$Q = \int_{a}^{b} U \frac{\log (r/b)}{\log (a/b)} 2\pi r \, dr = U\pi \left(\frac{b^{2} - a^{2}}{\log (a/b)} - a^{2} \right).$$

The average velocity is

$$\overline{U} = \frac{Q}{\pi(b^2 - a^2)} = U\left(\frac{1}{\log(a/b)} - \frac{a^2}{b^2 - a^2}\right).$$

The stress at the boundaries is $\mu du/dr$, which is $\mu Ur^{-1}(\log{(a/b)})^{-1}$. The force on the boundary is hence

$$-(2\pi bL)\frac{\mu U}{b\log\left(a/b\right)}-(2\pi aL)\frac{\mu U}{a\log\left(a/b\right)}=\frac{2\pi L\mu U}{\log\left(b/a\right)}.$$

It acts in the direction of *U*.

5 A is real so $\psi=2Axy$. Streamlines are lines of constant $\psi=xy$, i.e. hyperbolae. The major and minor axes are the coordinate axes. The velocity field is 2A(x,-y), so if A>0 the flow goes away from the y axis, and if A<0 it goes away from the x axis. We have $|u|=2|A|\sqrt{x^2+y^2}=2|A|r$, so the speed is everywhere proportional to the distance from the origin. Call the sides 1, 2, 3 and 4 going anticlockwise and starting at the origin. The normal velocity is 0 for sides 1 and 4, so the mass and momentum fluxes through them are zero. For the other sides, the mass fluxes out are

$$Q_2 = \int_0^l \rho u \, dy = \int_0^l \rho 2Al \, dy = 2Al^2 \rho, \qquad Q_3 = \int_0^l \rho v \, dx = \int_0^l \rho (-2Al) \, dy = -2Al^2 \rho;$$

their sum is zero as expected. The momentum fluxes out in the x- and y-directions are

$$M_2 = \int_0^l \rho u^2 \, dy = \int_0^l \rho (2Al)^2 \, dy = 4A^2 l^3 \rho,$$

$$M_3 = \int_0^l \rho u v \, dx = \int_0^l \rho (2Ax)(-2Al) \, dy = -2A^2 l^3 \rho$$

and

$$N_2 = \int_0^l \rho u v \, dy = \int_0^l \rho(2Al)(-2Ay) \, dy = -2A^2 l^3 \rho,$$

$$M_3 = \int_0^l \rho v^2 \, dx = \int_0^l \rho(-2Al)^2 \, dy = 4A^2 l^3 \rho.$$

Their sum is not zero (so there must be other terms in the steady momentum balance).

6 Units: ω is inverse time $[T]^{-1}$ and λ is length [L]. The units of other quantities are

$$h:[L], g:[L][T]^{-2}, T:[M][T]^{-2}, \rho:[M][L]^{-3}, \mu:[M][L]^{-1}[T]^{-1}.$$

We have seven parameters and three units (length, time and mass) so we can construct 7-3=4 dimensionless groups. Four possible non-dimensional groups are

$$\omega\sqrt{\frac{h}{g}}, \qquad \frac{\lambda}{h}, \qquad \frac{T}{\rho g h^2}, \qquad \frac{\mu}{\rho\sqrt{gh^3}}.$$

Hence we have

$$\omega = \sqrt{\frac{g}{h}} F\left(\frac{\lambda}{h}, \frac{T}{\rho g h^2}, \frac{\mu}{\rho \sqrt{g h^3}}\right).$$